A Study on the Search of Optimal Aquaculture farm condition based on Machine Learning

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Abstract The demand for aquatic products in the domestic and overseas is increased, so that the aquaculture industry can achieve high performance by controlling and standardizing the production even with a relatively small amount of resources compared with existing fisheries. However, traditional method has problems of low productivity such as natural disasters and ecosystem pollution, and it is necessary to develop a new culture system that can move to the optimal culture site. In order to find the optimal location, you need to collect and analyze the necessary data such as temperature and DO in real time. Data analysis was performed by using K-means clustering method based on machine learning, so that it was possible to decision when and where to move the farm by repeated unsupervised learning. The proposed research could solve the problems of low productivity such as natural disasters and ecosystem pollution if applied to regressive fish farmers.

Key Words : K-means clustering, Machine learning, Unsupervised learning, Aquaculture
the aquaculture industry has grown very rapidly, reaching over 8.8%. Demand for aquatic products is continuously increasing worldwide. However, the increase in the production and supply of aquatic products has not been able to keep pace with demand. Generally speaking, “food” means that grain is the most important position, but fisheries food is also a second food, and its role and functions are gradually expanding. However, the supply of natural fisheries through traditional fishery has already reached its limit, and there is no way to improve the supply power beyond the aquaculture. Aquaculture has developed into an important source of aquaculture around the world, but there are limits to the development of marine aquaculture due to the risks of natural disasters, marine pollution and competition for marine space use. The risks of natural disasters, marine pollution, and competition for marine space use reduce productivity, so if any one of them is resolved, the problem of increasing the supply of marine aquatic products will be solved. It is necessary to pursue economic efficiency and increase competitiveness of the aquaculture industry by making it possible to optimize the demand and supply of marine products by combining advanced technology. Therefore, in this study, we use the data obtained in real-time to analyze when and which point is the optimal condition, and use the artificial intelligence instead of human decision based on the analyzed data to determine the optimal position and point I have studied how to go.

II. A aquaculture industrial trends

The global fish market is a phenomenon in which supply to demand is shrinking, and this trend is expected to continue to accelerate in the future. Supply of wild fishery resources is declining due to environmental factors such as abnormal weather and natural disasters. Therefore, aquaculture is not only a source of aquaculture in the world, but also the most promising industry in the age of life, and its importance is increasing. It is time to cultivate a high value-added aquaculture industry connected with future life industry and government industry. The world is already aware of this fact and thinks that the only alternative to the future supply of fisheries food is efficient aquaculture. Therefore, research efforts are being made in the development of aquaculture not only in developed countries but also in developing countries. The farms within the UNESCO-designated area of Hallyeosaoddo are controlled by people for about 3 to 4 months a year. During this period, the farm environment (collection of data, transmission of CCTV data) can not be managed. Figure 1 shown the system configuration transmitting data from ocean to land.

Real-time data collection and analysis of offshore seawater can detect the possibility of massive death of caged aquatic products due to lack of cold water and dissolved oxygen. In order to prevent serious damage to fishermen and national fishermen, it is necessary to establish basic technology to prevent rapid disasters and disasters. Therefore, information necessary for domestic fisheries forms such as fishery environment, ocean observation information, and aquaculture information should be provided in real-time by One-Stop. The information required for aquaculture is basically temperature and DO. So, it is possible to judge the optimum position by receiving the data of the
temperature and the DO amount in real time. The various information provided will identify the optimal conditions under which the fish can be nurtured. Optimal conditions and locations will be recorded so that you can know when and where to grow. Figure 2 shown a list of more than 7000 data provided.

Therefore, if the fishery moves autonomously on the basis of the analyzed data, fish growth will become strong.

III. Data Analysis method

1. Unsupervised learning

Artificial intelligence imitates human brain and neuron neural network to make computers and robots think and act like humans. We can distinguish dogs and cats very easily from photographs, but computers do not distinguish between them. To that end, a method called Machine Learning was devised. There have already been many machine learning algorithms for how to classify data. Decision trees, Bayesian networks, support vector machines (SVMs), artificial neural networks (ANNs), and clustering are examples. If there is an error in the representative method of machine learning, the error is corrected until it returns to stable operation. So we choose clustering method which is one of the methods of machine learning. Clustering is the process of partitioning a group of data points into a small number of clusters. This algorithm is a kind of self learning, and plays a role of labeling the input data which is not labeled.

2. Clustering implementation

The term "k-means" was first used by James MacQueen in 1967,[1] though the idea goes back to Hugo Steinhaus in 1957.[2] The standard algorithm was first proposed by Stuart Lloyd in 1957 as a technique for pulse-code modulation, though it wasn’t published outside of Bell Labs until 1982.[3] In 1965, E. W. Forgy published essentially the same method, which is why it is sometimes referred to as Lloyd-Forgy.[4] The k-means clustering algorithm is part of the clustering method.[5][6] The partitioning method divides the given data into several partitions (groups). For example, assume that n data objects have been input. In this case, the partitioning method divides the input data into k groups smaller than or equal to n, where each cluster forms a cluster. In other words, we divide the data into k groups of one or more data objects. In principle, optimal partition achieved via minimising the sum of squared distance to its "representative object" in each cluster.[7] In clustering, the efficiency of clustering can be increased by selecting initial seed points using principal component analysis.[9] There are K-Means clustering methods that determine clusters through distribution of data and DBSCAN(Density-based spatial clustering of applications with noise) method using density of other data. DBSCAN is a data clustering algorithm proposed by Martin Ester, Hans-Peter Kriegel, Jörg Sander and Xiaowei Xu in 1996. It is a density-based clustering algorithm: given a set of points in some space, it groups together points that are closely packed together (points with many nearby neighbors), marking as outliers points that lie alone in low-density regions (whose nearest neighbors are too far away).[10][11] DBSCAN is one of the most common clustering algorithms and also most cited in scientific literature[10][11]. DBSCAN is able to do algorithm that classifies clusters and noise in a word.

![Table](image)

**Fig. 2.** More than 7,093 data lists
A cluster is a set of all data vectors accessible from a core vector, and the cluster is created around the core vector. The advantage of the DBSCAN over the K-means algorithm is that it does not need to determine the number of clusters. In fact, DBSCAN is one of the density models and uses data location information like K-Means. Therefore, the problem of noise also has the advantage that the noise data does not affect the cluster because the DBSCAN separates the noise data separately.

IV. Experiments

In this paper, R program is used to cluster more than 7,000 real-time temp and Do data collected over one month. R program is not only an open source language but also a statistical program that can be used freely by using libraries. We analyze the collected data in real time and make it possible to stabilize even if an error occurs in finding an optimal place. More than 7,000 data collected in real time are represented by K-means clustering graph. The collected data were clustered using K-means algorithm. Then, centroid and distance were calculated on the collected data. The data that were distant from the centroid were judged to be meaningless data. The centroid exists in the cluster given in figure 3 and the distant object is ignored.

However, as a result of analyzing a large amount of data with the K-means algorithm, meaningless data was continuously clustered with meaningful data. In other words, noise is recognized as meaningful data. So we applied the DBSCAN algorithm. The DBSCAN algorithm takes two parameters. First, it defines the surrounding space. Second, it is necessary to define how many pieces of data exist in the surrounding space. (In the pseudo code, eps defines the space, and MinPts defines the number of data in the surrounding space.) If MinPts is large, care should be taken as important values can be ignored, and caution should be taken when small, as meaningless values can be included in clusters. Also note that if you make a large eps, the number of clustering may be smaller than expected, and if you hold it small, the number of clustering can be quite different from what you expected. Therefore, the optimal values were clustered by eps = 0.41 and MinPts = 70. The results are shown in Figure 4.

The result shows that three clusters have been created. To derive the above result, the pseudo code is as follows.
>library(fpc)
>setwd("/Users/ChoiEunSoo/Desktop")
>de <- read.csv("de.csv")
>ds <- dbscan(de, eps=0.41, MinPts=70)
>plot(ds,de)

Data collected in real time from marine aquaculture will be repeatedly analyzed in a specific area, and the analyzed data will be linked with GPS to find an optimal marine aquaculture site.

V. Conclusion

Compared with fisheries, the aquaculture industry is capable of achieving high performance by controlling production and standardization with relatively little input of resources. However, traditional forms have problems of low productivity such as natural disasters, natural ecosystem pollution, and high mortality rate. Among them, it is important to find an optimal farm because the fish farm location is directly related to productivity. In order to find the optimal place, you should find the optimum conditions for the culture place. In order to find the optimal condition, necessary data such as temperature and DO were collected and analyzed in real time. Data analysis was performed by using K-means clustering method based on machine learning, and repeated unsupervised learning was performed to exclude data not existing in the cluster. As a result, we analyzed the useful data by filtering the error data so that we could decide the best place to do when and where to fish farm. The proposed study could solve the problems of low productivity such as natural disasters and ecosystem pollution if it is applied to fish farms.

References
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